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RobotC Virtual Worlds - Robo Slalom II
RobotC and EV3 Sensors and Loops Part 1
Wester's RobotC for Automation
Au026 Robotics - EP 07 - LED Lights
Quick Intro to ROBOTC

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Programming Touch Sensors
RobotC Intro 07 Line Tracker

Photo Interrupter Circuit Example(Alarm Circuit, Card Key Lighting)
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Sensors for Every Leading Edge Detection Application
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Photoelectric Sensors - Retro-Reflective - Part 2 - Datalogic
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RobotC White Loops
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POE 3.1.2
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The VEX light sensor allows the robot to sense the ambient light in a room. Unlike the Line Tracking Sensor, the Light Sensor does not generate any light, it only senses the amount of light already present in an area. The Light Sensor is an analog sensor, and it returns values in the range of 0 to 4095.

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Light The Light sensor, also known as the Reflection sensor, returns values ranging between 0 and 4095. 0 is the lightest reading and 4095 is the darkest.

VEX2 Sensors Overview - ROBOTC API Guide
The NXT Light Sensor has a range of states between 0 and 100. The lower the number, the darker the reading is. The higher the number, the lighter the reading is. Below is a simple line-following program that uses only one NXT Light Sensor.

NXT Sensors Overview - ROBOTC API Guide
PIC Sensors Overview For ROBOTC
PIC Sensor functions, check out the PIC Sensor Functions page!
The VEX is equipped with 16 sensor ports. These can be either analog (e.g. voltage level from a photocell detecting light intensity) or digital (e.g. a touch or switch sensor).

VEX Sensors Overview - ROBOTC API Guide
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The first thing we need to do is configure RobotC for our light sensors. Light Sensor Overview Robotc - yycdn.truyenyy.com
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Touch Sensors Overview Bumper Switch
The Bumper Switch, above, is a type of touch sensor for the VEX. Due to its size and construction, it is better suited for tasks such as wall detection. Limit Switch
The Limit Switch is another form of touch sensor for VEX. It is more suited for detecting smaller motions that might not trigger the bumper sensor. Both then Bumper Switch and the Limit Switch ...

Touch Sensors Overview - ROBOTC
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The center of the sensor can rotate roughly 265 degrees and outputs values ranging from 0-1023 to the Vex Microcontroller. When mounted on the rotating shaft of a moving portion of the robot, such as an arm or gripper, the Potentiometer provides precise feedback regarding its angular position.

Potentiometers Overview - ROBOTC
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Analog Sensors: Light Sensor: 0 (light) to 4095 (dark). Potentiometer: 0 to 4095. Minimum and maximum values are achieved at opposite ends of travel of the potentiometer and may vary slightly from one potentiometer to another. Line Follower: 0 (light) to 4095 (dark). Values will vary depending on the surfaces being detected and the ambient lighting of the environment. Gyro Sensor:-3600 (360.0 ...

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ROBOTC has a debugging capability that enables unparallelled, interactive access to the robot as your program is running. Using the debugger will significantly reduce the time it takes to write programs and find erros in your code.

The ROBOTC Debugger Overview
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Part 1: A Flashlight Responding to Light. Open the PLTW ROBOTC template. Click File, Save As, select the folder that your teacher designated, and then name the file A3_1_4_Part1. In this activity you will use all of the testbed input and outputs. Go to the Motors and Sensors Setup window. Configure the Motors and Sensors Setup to reflect the inputs and outputs to be used. Note that additional ...

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